

0	Front Page
1	General Survey Information
2	Nominal Configuration
3	Nominal CMP Coverage
4	Survey Area
5	Geodetic Parameters
6	Recording System Parameters
7	Streamer Parameters
8 (1)	Cable #1 Layout
8 (2)	Cable #2 Layout
8 (3)	Cable #3 Layout
8 (4)	Cable #4 Layout
8 (5)	Cable #5 Layout
8 (6)	Cable #6 Layout
8 (7)	Cable #7 Layout
8 (8)	Cable #8 Layout
9	Cable Section Nominal Offsets
10	Cable Active Section Offsets
11	Source Parameters / Sub Array Layout
12	Source Layout
13	Navigation System Parameters
14	P2/94 Naming Conventions
15	Vessel & Antennae Offsets
16	Streamer Offsets
17	Source & Towfish Offsets
18	Parameter Changes

Woodside Energy Ltd  
Job No : 1999-35D-EH  
Investigator 3D  
Victoria, Australia  
6 Cable / Dual Source

# **WESTERN PRIDE Party 140**

## **3D PARAMETER REPORT**



Western Geophysical



<b>CLIENT</b>	<b>: Woodside Energy Ltd</b>
<b>SURVEY</b>	<b>: Investigator 3D</b>
<b>AREA</b>	<b>: Bass Straits, Victoria, Australia</b>
<b>JOB #</b>	<b>: 1999-035D-EH</b>
<b>DATE</b>	<b>: 19th February - 2nd April 2000</b>
<b>SEQUENCES</b>	<b>: 081-147 : Six Cable Configuration</b>

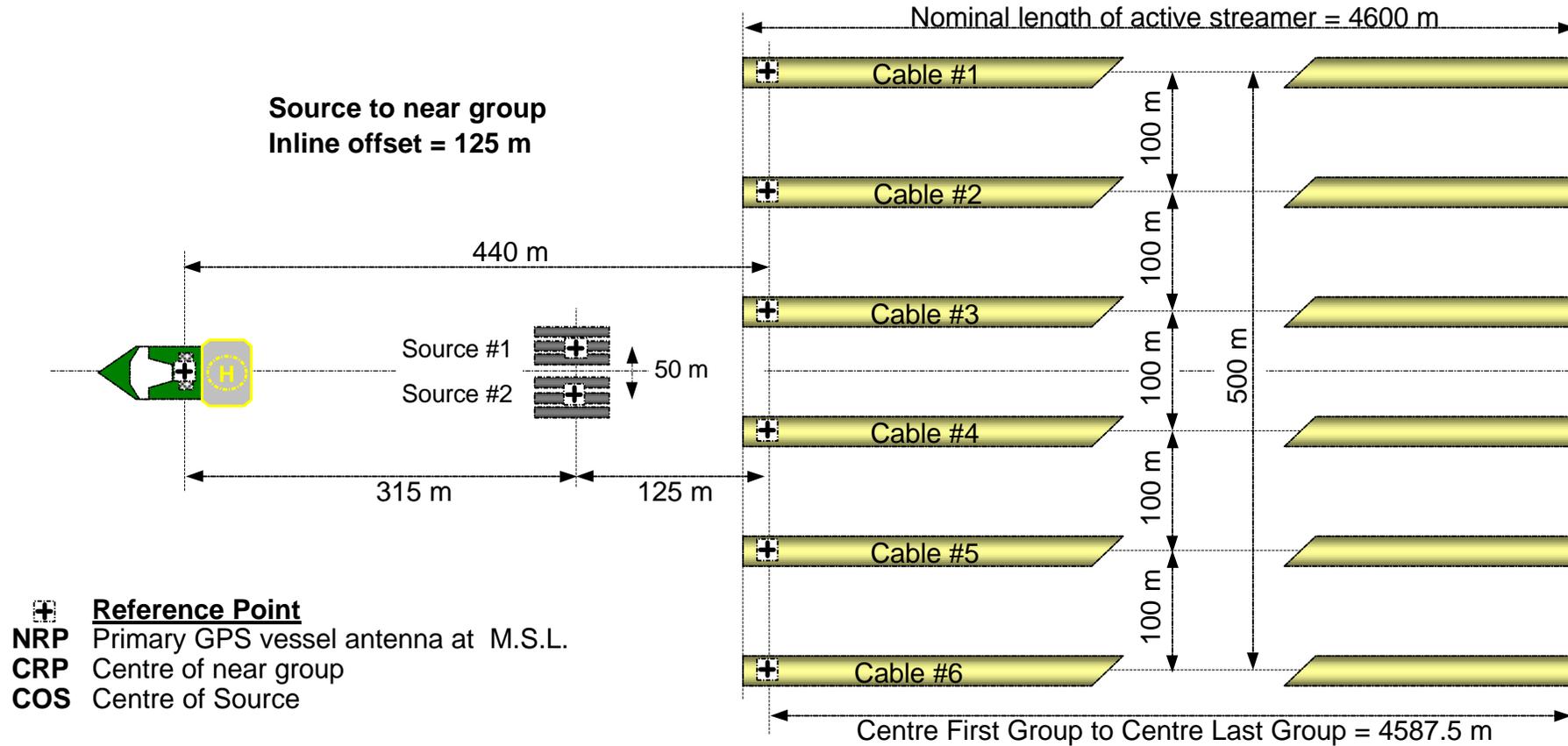
# GENERAL SURVEY PARAMETERS



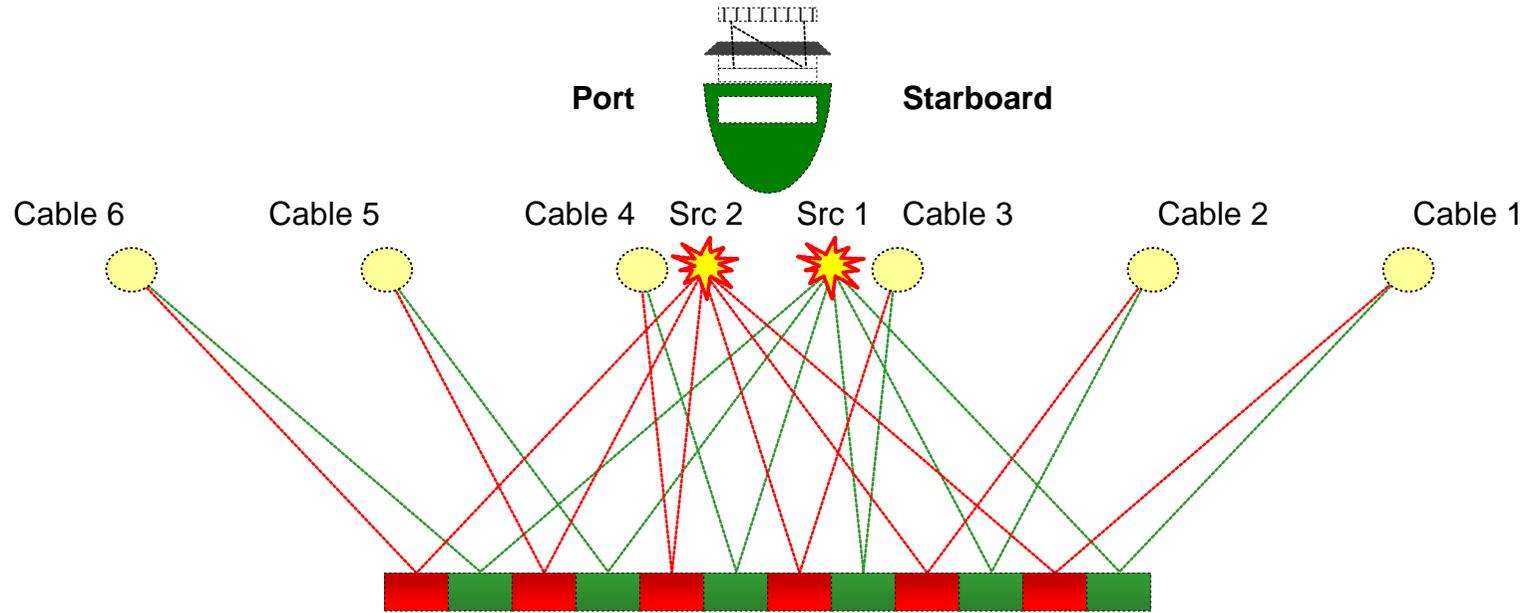
**Woodside Energy Ltd.**  
**Investigator 3D**  
**Bass Straits, Victoria, Australia**  
**1999-35D-EH**

<b>Recording System:</b> (MSX/CRS)	L.C. Filter	2 Hz @ 12 dB/Oct
	H:C. Filter	206 Hz @ 264 dB/Oct.
	Record Length	4608 ms
	Sample Rate	2 ms
<b>Seismic Cable:</b> (TMS Solid Streamer)	Number of cables	6
	Number of channels	368 Per Cable, 2208 Total Seismic
	Cable length	4600 m
	Group Interval	12.5 m (centre to centre)
	Depth	6 m (+/- 1 m)
<b>Sources:</b>	Number of sources	2 Arrays
	Source type	Tuned Air Gun Array
	Volume	2250 cu.in.
	Pressure	2000 p.s.l. (+/- 150 p.s.l.)
	Depth	5 m (+/- 0.5 m)
	Shot Point Interval	12.5 m
<b>Configuration:</b>	Inline Source to Near Group	125 m (no greater than 150 m)
	Source Separation	50.00 m
	Cable Separation	100 m between cables, 500 m total spread
<b>Coverage:</b>	Inline CMP Cell Length	6.25 m (12.5 m used in coverage displays)
	Cross Line CMP Cell Width	25.0 m
	Nominal Fold	92
	Acquisition Line Azimuth	009°/189°
<b>Vessel Positioning:</b>	System #1	Racal Multifix Differential GPS
	System #2	Fugro MRdGPS Differential GPS
	QC System	QPS Muliref Differential GPS
<b>Onboard Processing:</b>	Seismic Processing	Omega (Ver 1.8.0)
	Navigation Processing	Unavchk (Ver 1.9.6)

# NOMINAL CONFIGURATION



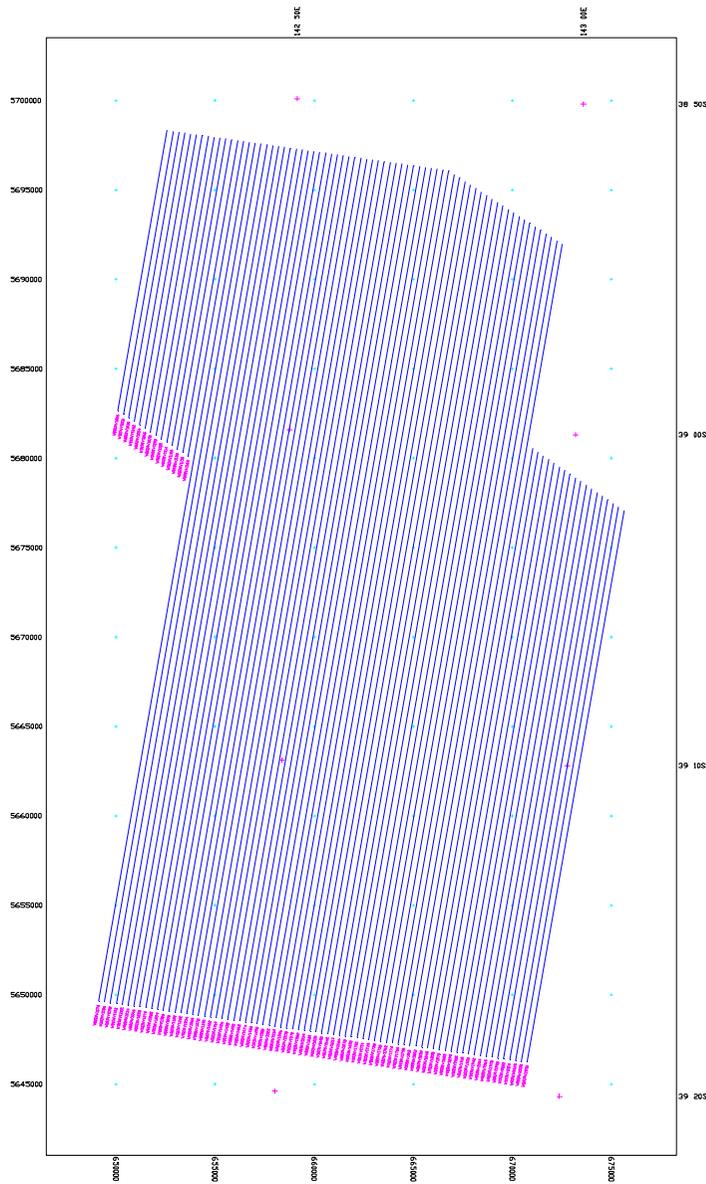
# NOMINAL CMP COVERAGE



-  Acquired CMP line
-  Acquired CMP line
-  Source
-  Streamer
-  Raypath from stbd source (1)
-  Raypath from port source (2)

**Diagram shows vessel from astern (pointing in to page)**  
**Cell width = 25 m**  
**Cell Length = 6.25 m (12.5 m for coverage displays)**  
**Shotpoint Interval = 12.5 m Flip Flop (25 m per CMP Line)**  
**Nominal Fold = 92**

# SURVEY AREA



## 6 Cable Waypoints Full Fold Area

	<b>Easting</b>	<b>Northing</b>
1	649973.0	5682748.5
2	652442.7	5698341.7
3	666764.2	5696073.4
4	672656.9	5691887.5
5	670871.6	5680615.5
6	675759.3	5676955.8
7	670890.3	5646214.0
8	648988.3	5649683.0
9	653800.6	5680066.7

# GEODETIC PARAMETERS



## Geodetic Parameters

**Local Datum** AGD84  
 Spheroid Australian National Spheroid  
 Semi-major axis 6378160.000  
 1/flattening 298.25

**Satellite Datum** WGS 84  
 Spheroid WGS 84  
 Semi-major axis 6378137.000  
 1/flattening 298.257224

## **Datum Shift**

Shift Parameters From WGS 84 to Local Datum  
 Dx = +116.0 Rx = -0.23 arc sec\*  
 Dy = +50.47 Ry = -0.39 arc sec\*  
 Dz = -141.69 Rz = -0.344 arc sec\*  
 Scale factor= -0.0983 ppm \*as entered in Spectra

**Mapping Projection** AMG ZONE 54 (UTM)  
 Origin of Latitude 000° 00' 00.00" N  
 Origin of Longitude 141° 00' 00.00" E  
 False Northing 10,000,000.0 m  
 False Easting 500,000.0 m  
 Central Meridian 141° 00' 00.00" E  
 Scale factor at CM 0.9996  
 Grid Units Metres

**Vertical Datum** Mean Sea level

## Binning Parameters

### Binning Systems

Online real-time binning	Spectra	Ver 7.6.5
Post line binning	Reflex	Ver 1.7.2

### Binning Grid

Map Grid Origin Easting	643880.97	(bin centre)
Map Grid Origin Northing	5647960.68	(bin centre)
Map Grid Bearing (°)	009.00°	(In-line axis)

	<u>In-line</u>	<u>X-line</u>
Bin Grid Extent (m)	53587.5	27475
Bin Number at Origin	801	978
Bin Number Increment	1	1
Bin Dimensions (m)	12.5	25
Apply scale factor	No (using mapping grid distances)	

## **Nominal Offset Distribution**

Minimum Offset (m)	150
Maximum Offset (m)	4750
Offset Increment (m)	50

## **Coverage Groups**

	<u>Near Offset (m)</u>	<u>Far Offset (m)</u>
Nears	150	1300
Near Mids	1300	2450
Far Mids	2450	3600
Fars	3600	4750

# RECORDING SYSTEM PARAMETERS



Recording System  
System Version

**I/O Systems MSX**  
Version 2.0

Tape Interface System  
System Version

**Western Geophysicals CRS (Continuous Recording System)**  
3.0.2

MSX Record length  
CRS Record length  
Sample rate  
Time break  
Low Cut Filter  
High Cut Filter  
Multishot Acquisition

4.5 Binary Seconds (4608 ms)  
4.5 Binary Seconds (4608 ms)  
2 ms  
Co-incident with digital start  
2 Hz @ 12 dB/Oct.  
206 Hz @ 264 dB/Oct.  
Not used

Recorded data format  
Trace polarity  
Recording media type  
Maximum Number of Files per Cartridge

8058 SEG D - DMX  
positive pressure = negative number on tape = negative pulse on plot  
3M 3590 cartridge tapes  
400 (1 file contains 2944 channels at 4068 ms length + auxiliaries)

Number of Channels  
Channel set 1-6 (368 channels each)  
Channel set 7-12 (4 channels each)  
Channel set 13 (1 channel)  
Channel set 14 (1 channel)  
Channel set 15-18 (1 channel each)  
Channel set 19-27 (1 channel each)  
Channel set 28 (1 channel)  
Channel set 29 (64 channels at 512 ms)

2208 seismic + 104 auxiliaries  
Seismic data  
Waterbreaks  
Recording System Start  
Combined Timebreak  
Array Timebreak  
Spare  
Sample Count  
Gun signature

Real Time Data QC  
Camera Recorder

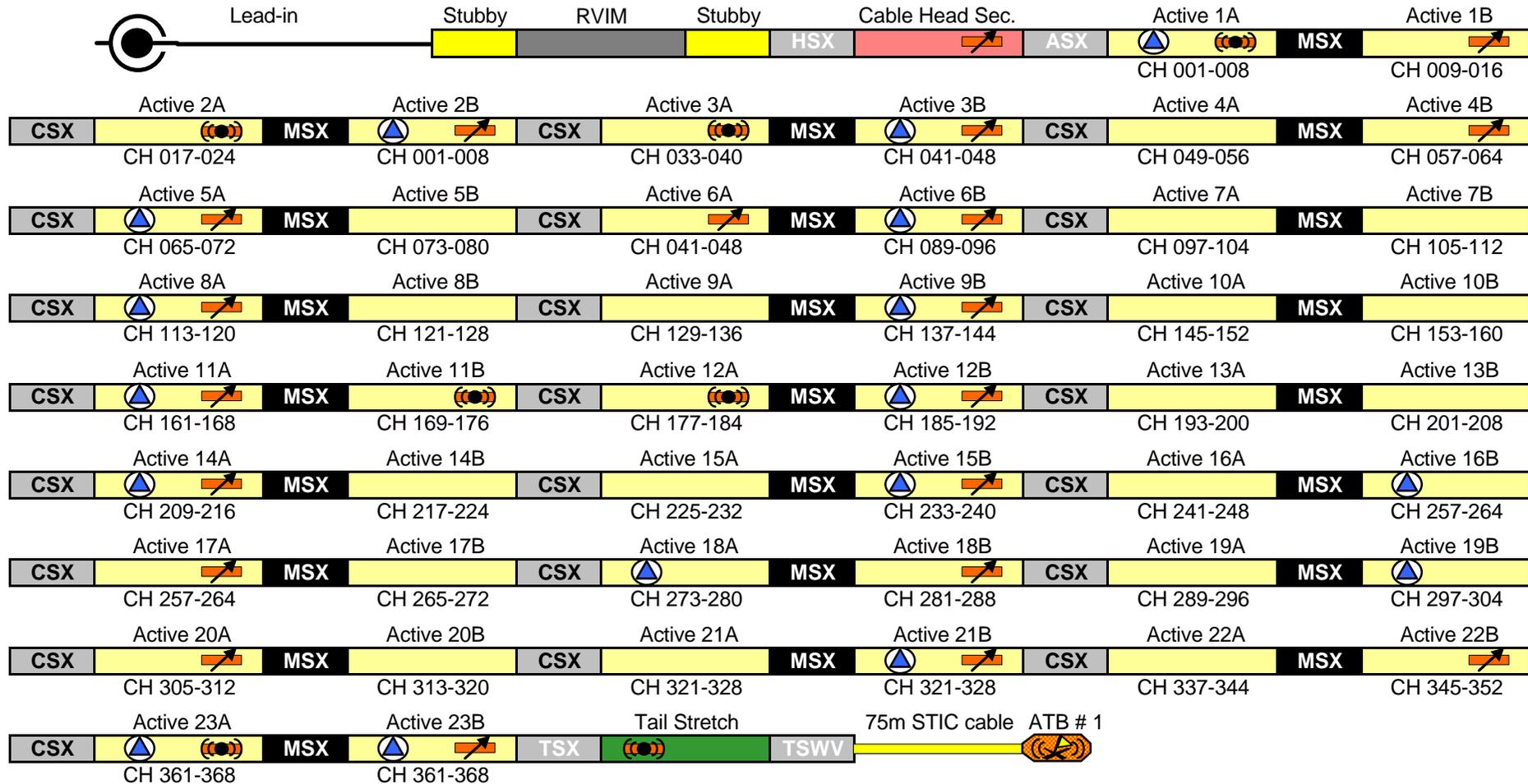
SeisView  
Enhanced Visualisation Processor (EVP)

# STREAMER PARAMETERS



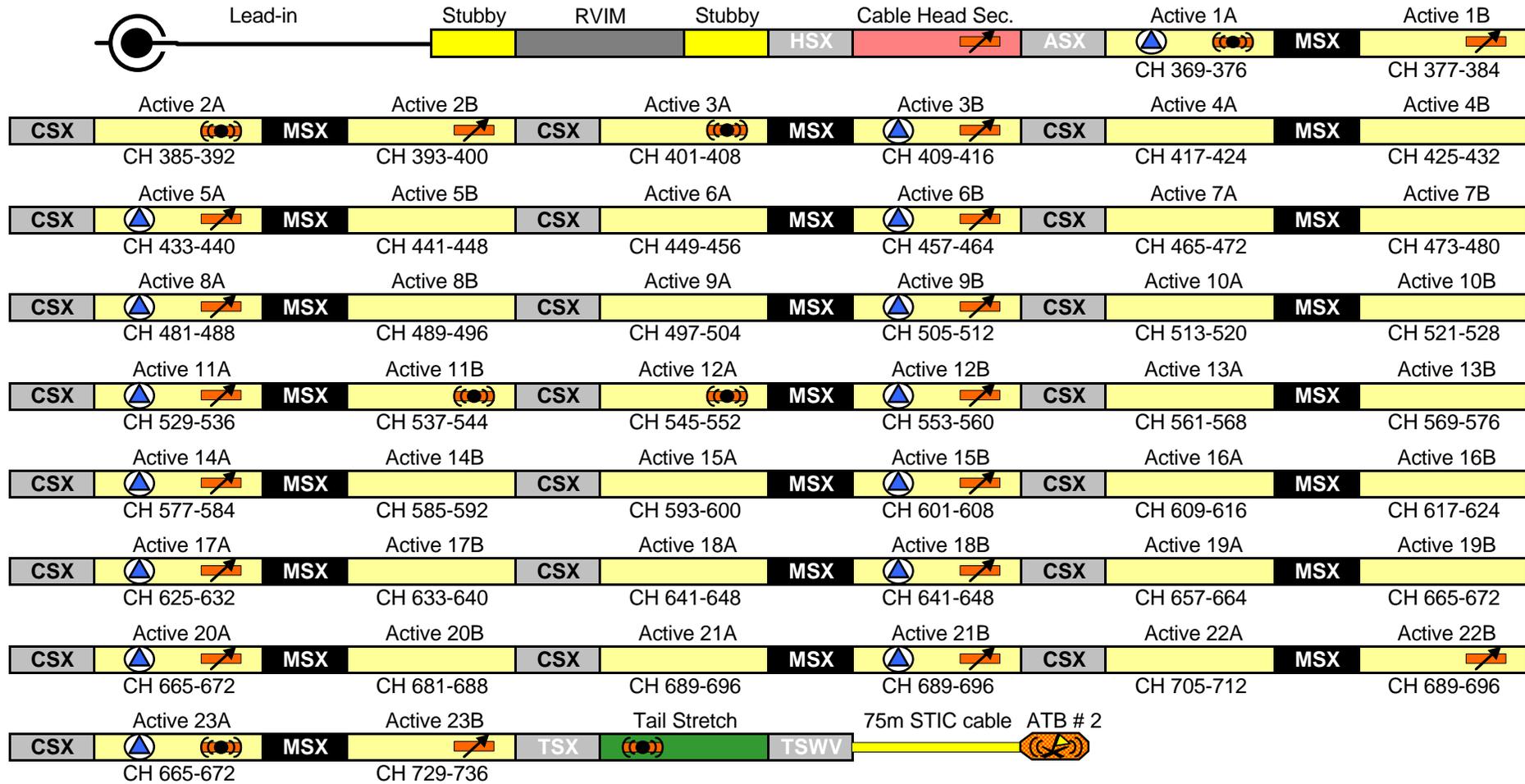
Streamer Type	<b>Thompson Marconi Sonar Solid Streamer</b>	
Number of Streamers	6	
Group Length	17.55 m	
Nominal Group Interval	12.5 m (12.45 m in Spectra / P294 for stretch calculation)	
Streamer Length	4600 m	
Streamer Depth	6.0 m +/- 1.0 m	
Streamer Separation	100 m inter-cable, 500 m total spread	
Number of Groups	368 total per cable, 2208 total seismic	
Nominal Section Length	100 m (46 sections per streamer)	
Number of Groups per Module	16 (group interval 12.5 m)	
Number of Groups per Section	8 (group interval 12.5 m)	
Streamer Sensitivity	14 V/Bar	
Hydrophone type	Piezo-electric Ceramic	
Number of Hydrophones per Group	14 (group interval 12.5 m)	
Trace numbering in SEG-D data	Near Group each cable =1	Far Group each cable = 368
Trace numbering in P1/90 data	Near Group Cable #1 = 1	Far Group Cable #1 = 368
	Near Group Cable #2 =369	Far Group Cable #2 = 736
	Near Group Cable #3 = 737	Far Group Cable #3 = 1104
	Near Group Cable #4 = 1105	Far Group Cable #4 = 1472
	Near Group Cable #5 = 1473	Far Group Cable #5 = 1840
	Near Group Cable #6 = 1841	Far Group Cable #6 = 2208
Compasses/Levellers	Input/Output Pro2000 Combined Compass/Birds	
Streamer Positioning	Input/Output Pro2000 Acoustics, Input/Output Pro2000 Compasses POSNET remote rGPS targets on each tailbuoy	

# CABLE #1 (STBD OUTER) LAYOUT



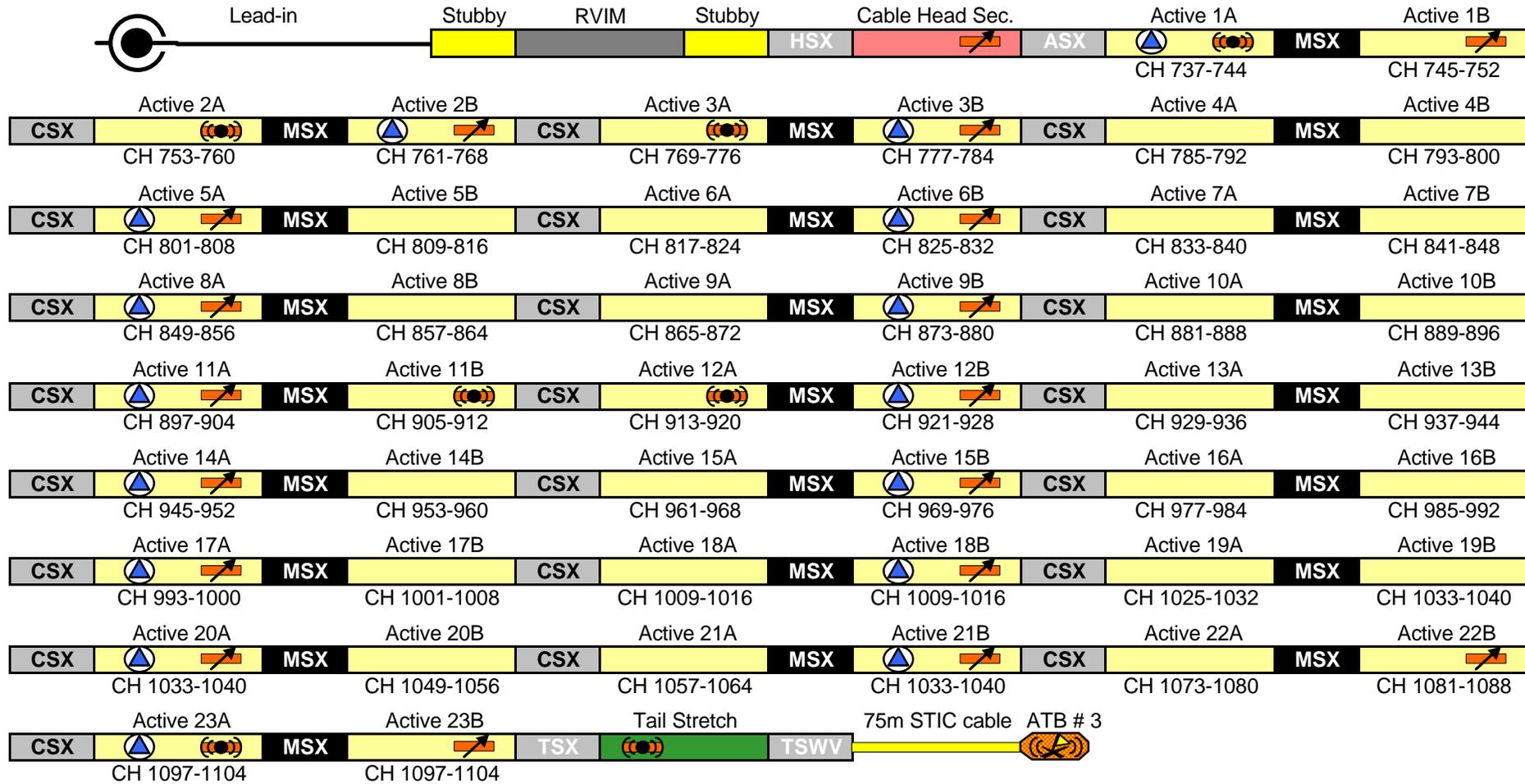
- |                    |                          |                                |                           |
|--------------------|--------------------------|--------------------------------|---------------------------|
| Stretch Section    | MSX Streamer Module      | ASX Auxilliary Streamer Module | Compass/ Bird             |
| Cable Head Section | CSX Connector Module     | TSX Tail Streamer Module       | Acoustic Pod              |
| Active Section     | HSX Head Streamer Module | TSWV Tail Swivel               | rGPS/Acoustic Tailbuoy    |
|                    |                          |                                | Streamer Retrieval Device |

# CABLE #2 LAYOUT



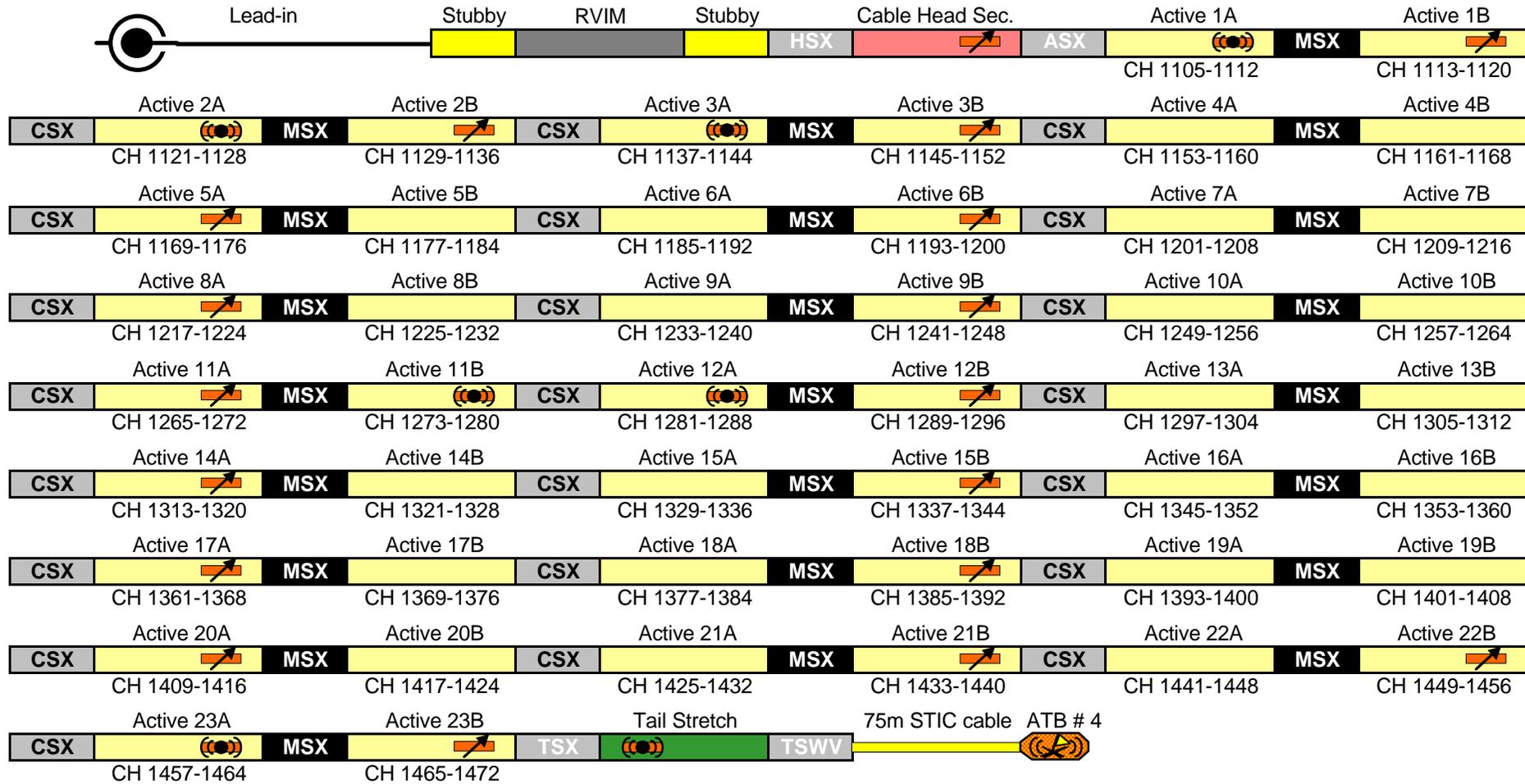
- |                    |                      |                            |                           |
|--------------------|----------------------|----------------------------|---------------------------|
| Stretch Section    | Streamer Module      | Auxilliary Streamer Module | Compass/ Bird             |
| Cable Head Section | Connector Module     | Tail Streamer Module       | Acoustic Pod              |
| Active Section     | Head Streamer Module | Tail Swivel                | rGPS/Acoustic Tailbuoy    |
|                    |                      |                            | Streamer Retrieval Device |

# CABLE #3 LAYOUT



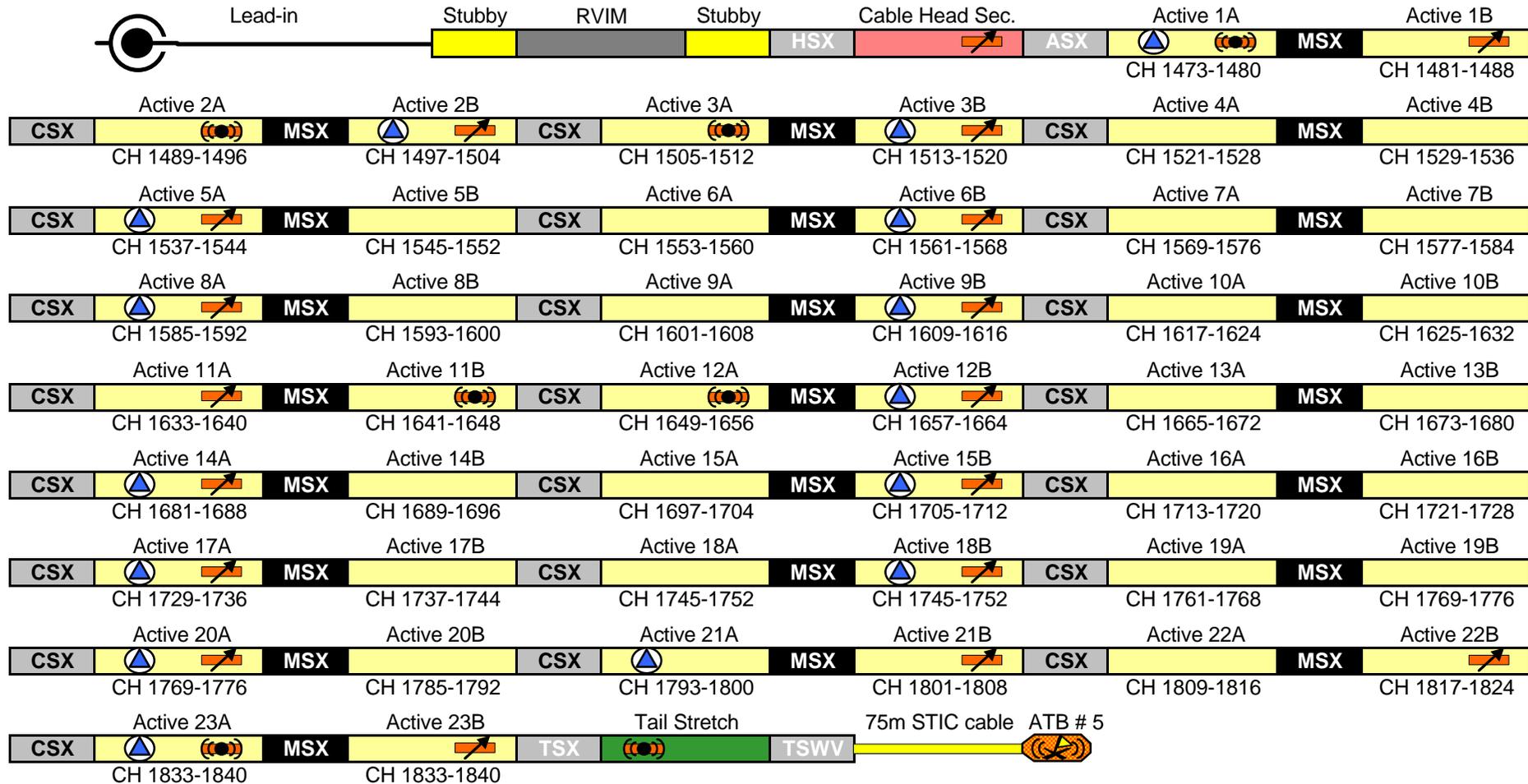
- |  |   |  |   |
|--|---|--|---|
|  Stretch Section    |  <b>MSX</b> Streamer Module      |  <b>ASX</b> Auxilliary Streamer Module |  Compass/ Bird             |
|  Cable Head Section |  <b>CSX</b> Connector Module     |  <b>TSX</b> Tail Streamer Module       |  Acoustic Pod              |
|  Active Section     |  <b>HSX</b> Head Streamer Module |  <b>TSWV</b> Tail Swivel               |  rGPS/Acoustic Tailbuoy    |
|  |   |  |  Streamer Retrieval Device |

# CABLE #4 LAYOUT



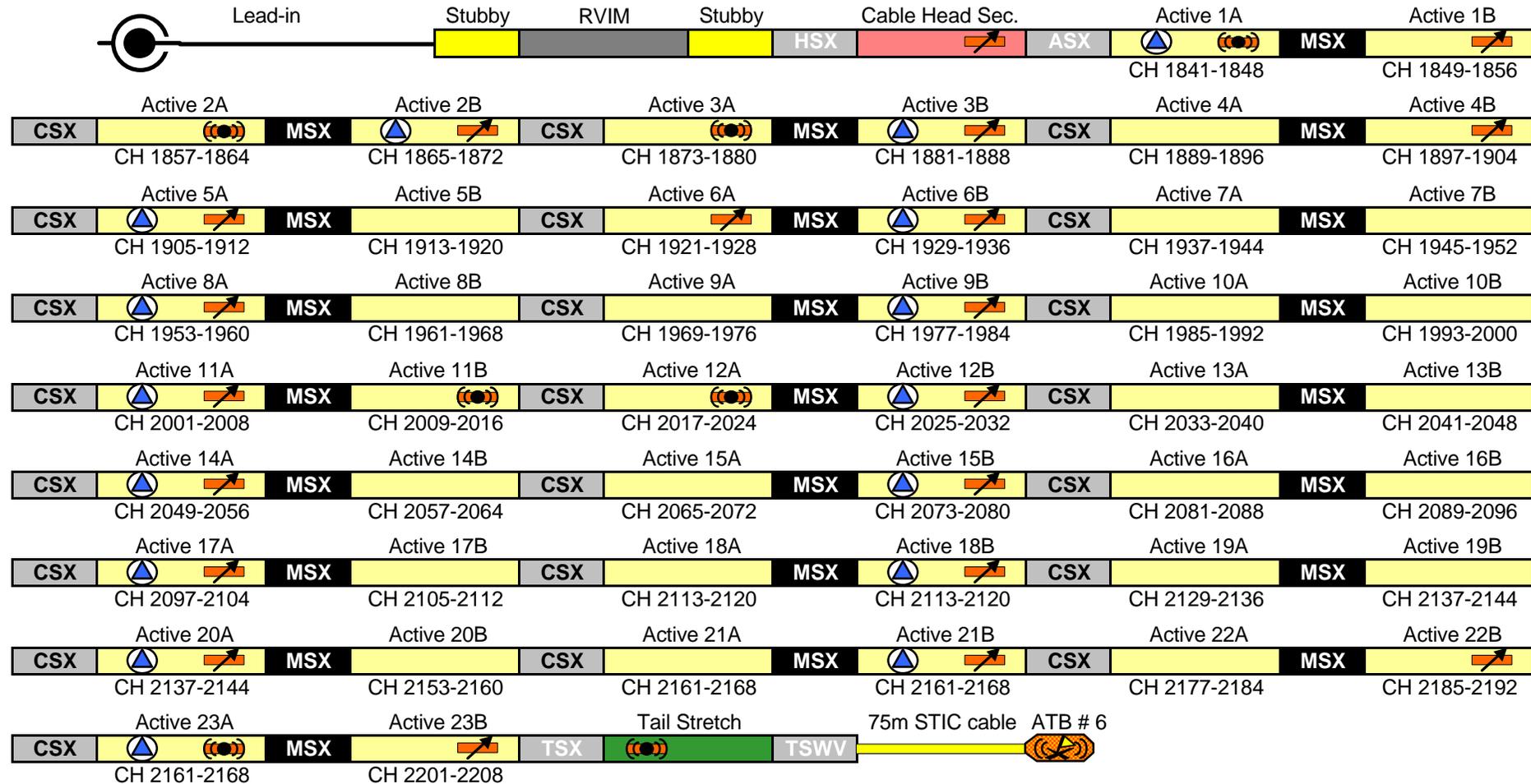
- |                    |                      |                            |                           |
|--------------------|----------------------|----------------------------|---------------------------|
| Stretch Section    | Streamer Module      | Auxilliary Streamer Module | Compass/ Bird             |
| Cable Head Section | Connector Module     | Tail Streamer Module       | Acoustic Pod              |
| Active Section     | Head Streamer Module | Tail Swivel                | rGPS/Acoustic Tailbuoy    |
|                    |                      |                            | Streamer Retrieval Device |

# CABLE #5 LAYOUT



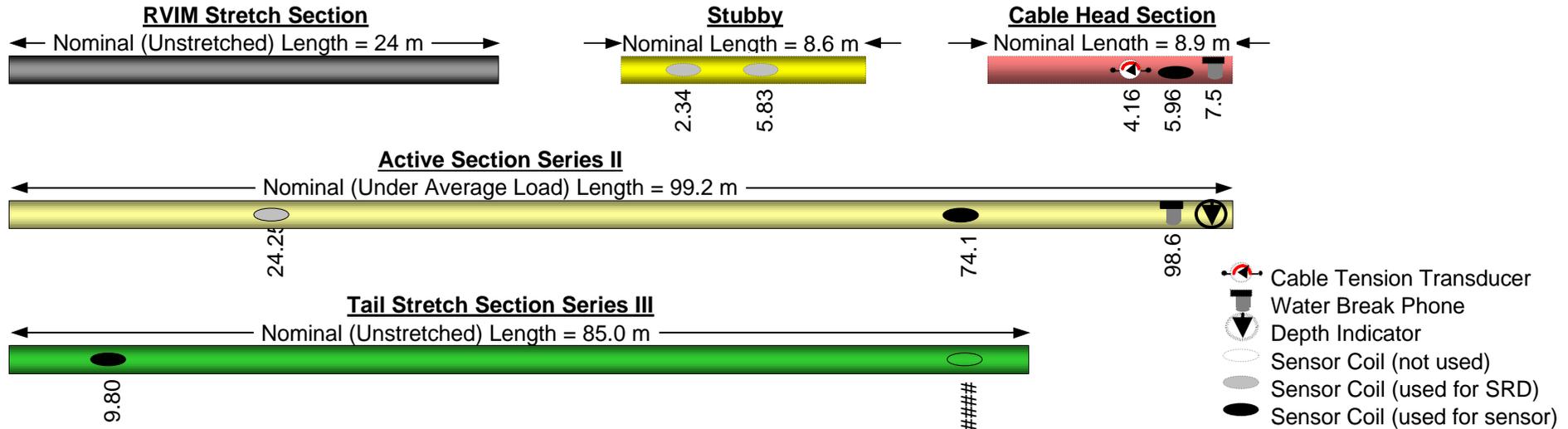
- |                    |                          |                                |                           |
|--------------------|--------------------------|--------------------------------|---------------------------|
| Stretch Section    | MSX Streamer Module      | ASX Auxilliary Streamer Module | Compass/ Bird             |
| Cable Head Section | CSX Connector Module     | TSX Tail Streamer Module       | Acoustic Pod              |
| Active Section     | HSX Head Streamer Module | TSWV Tail Swivel               | rGPS/Acoustic Tailbuoy    |
|                    |                          |                                | Streamer Retrieval Device |

# CABLE #6 (PORT OUTER) LAYOUT

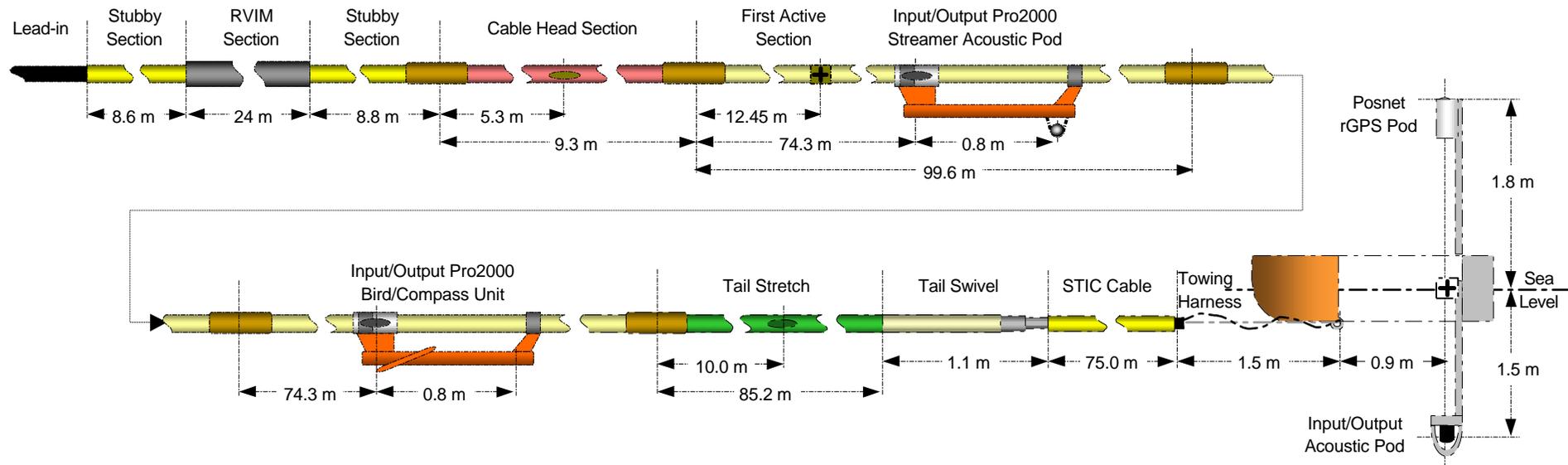


- Stretch Section
- Cable Head Section
- Active Section
- MSX Streamer Module
- CSX Connector Module
- HSX Head Streamer Module
- ASX Auxilliary Streamer Module
- TSX Tail Streamer Module
- TSWV Tail Swivel
- Compass/ Bird
- Acoustic Pod
- rGPS/Acoustic Tailbuoy
- Streamer Retrieval Device

# CABLE COMPONENT NOMINAL OFFSETS



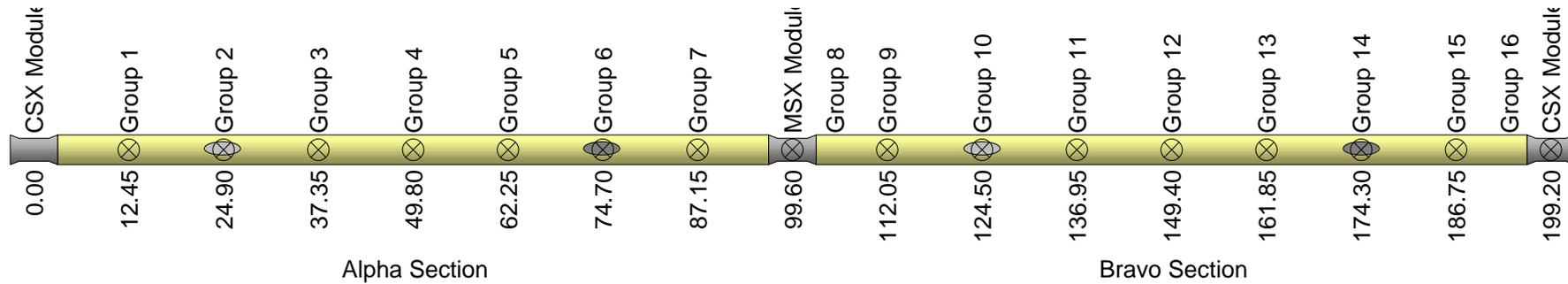
**NB** Modules are approximately 0.4 m long and are not included in the measurements given above



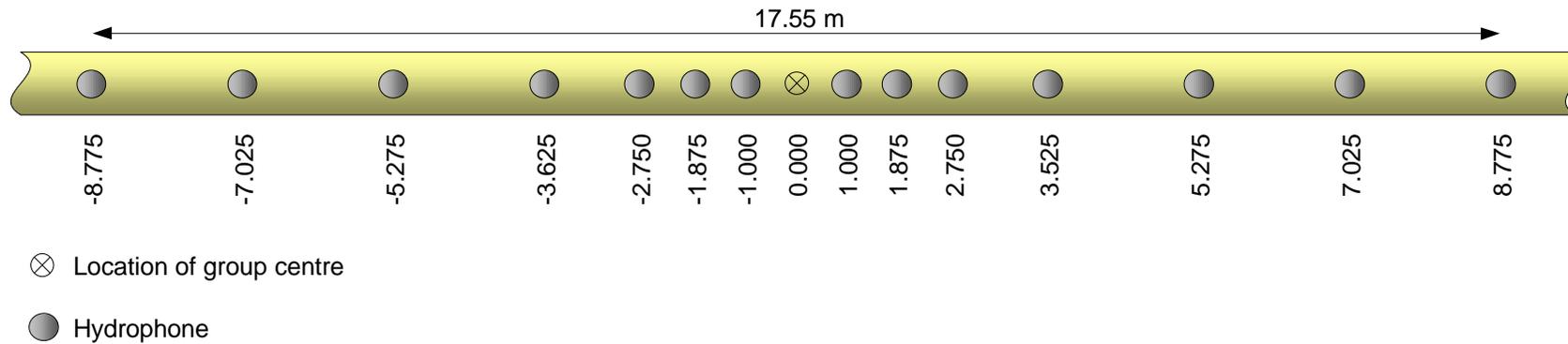
# GROUP AND HYDROPHONE LOCATIONS



## Active Section Assembly And Receiver Group Locations



## Receiver Group Hydrophone Locations

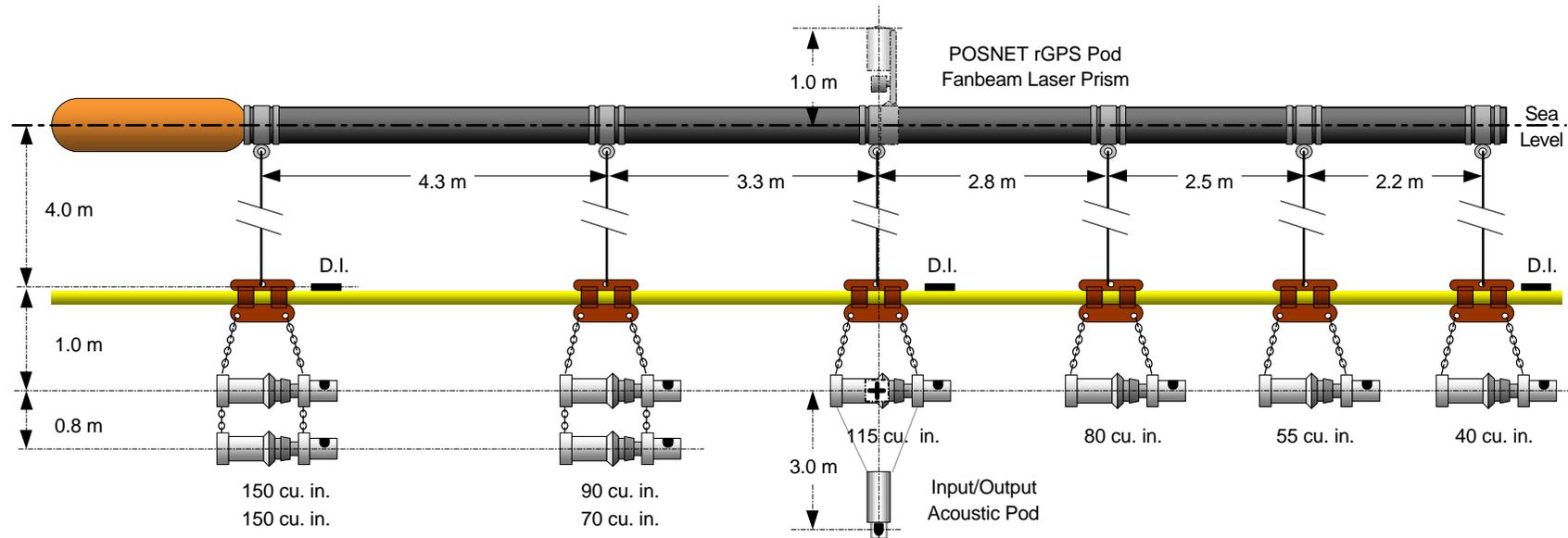


# ENERGY SOURCE PARAMETERS

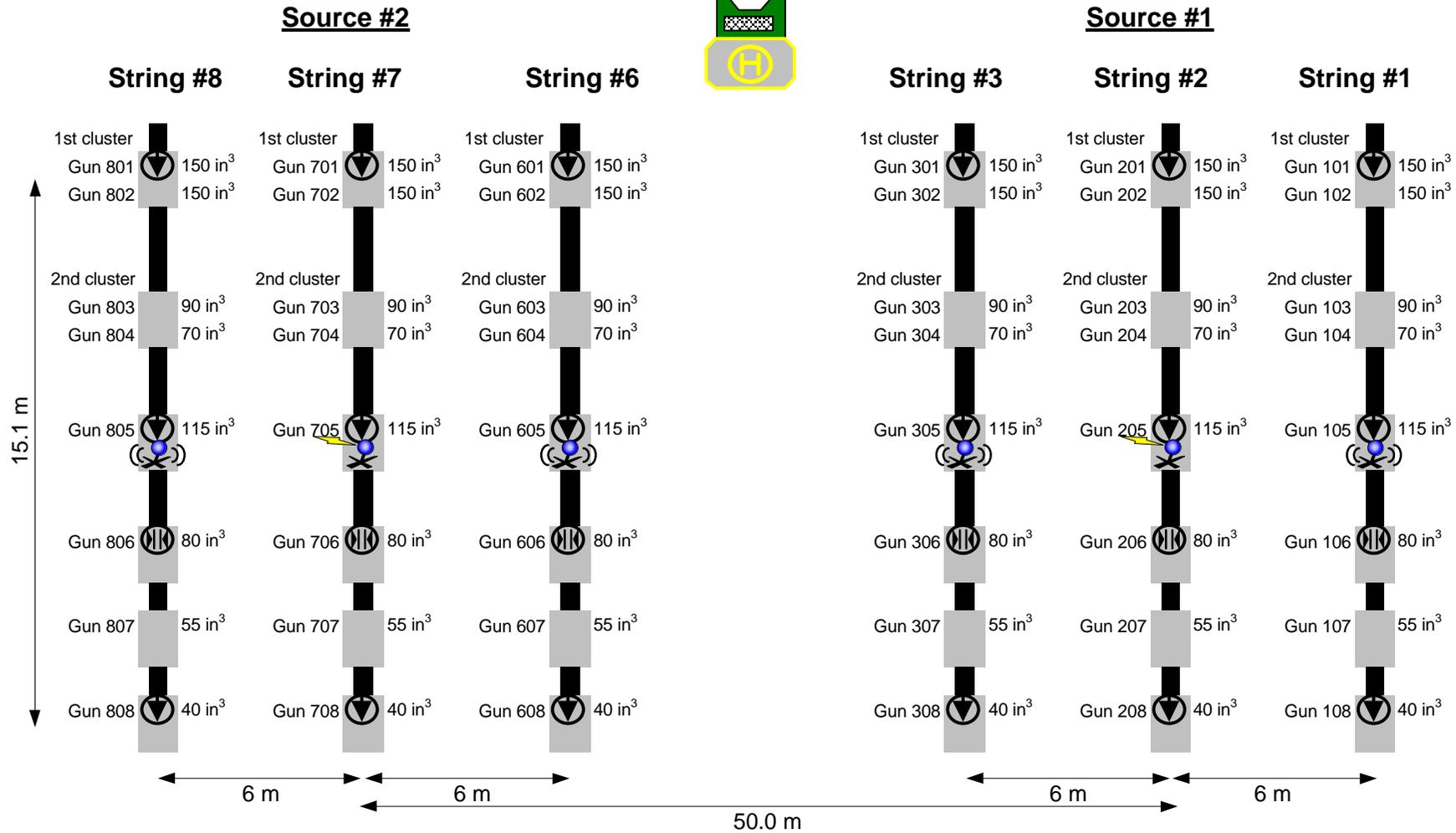


Energy Source Type	Tuned Air Gun Array	Gun depth	5 (±0.5) m
Air Gun Type	Sleeve Gun II	Gun Depth Monitoring	SSS OCM (Ver 1.7 with Y2K patch)
Number of Arrays	2	Gun Synchronisation	± 1 ms
Array Separation	50 m	Gun Synch. System	SSS OCM (Ver 1.7 with Y2K patch)
Pop Interval	12.5 m	Number of Sub-Arrays	3 per array, 6 total
Pressure	2000 (±150) p.s.i.	Sub Array Separation	6 m
Volume	2250 cu.in.	Sub Array Length	15.1 m
Source Output	74.1 bar-m (peak to trough 3-128 Hz) 40.7 bar-m (0 to peak)	Number Of Guns per Array	24
Bubble ratio	17.3:1	Near field hydrophone	1 phone per gun element (6 per sub array)

Source Positioning      Input/Output Pro2000 Acoustics; POSNET rGPS and Fanbeam laser reflective headbuoys



# ENERGY SOURCE LAYOUT



- Depth Indicator
- Pressure Indicator

- Co-located Posnet rGPS Pod and DigiCOURSE Acoustic CTX Pod
- Co-located Posnet rGPS Pod and Fanbeam Reflective Prism

# NAVIGATION SYSTEM PARAMETERS



<b>Data Acquisition System</b>	Spectra Integrated Navigation System RTNU (Real Time Navigation Unit)		Ver 7.6.5 Ver 7.6.5 (ILC)	
<b>Vessel Positioning</b>	Primary System Secondary System QC System Other System	Racal Multifix Differential GPS Fugro MRdGPS Differential GPS QPS Muliref Differential GPS Posnet Differential GPS	Ver 2.10 Ver 2.04.01 Ver 2.42 Ver 1.57	
<b>Source/Streamer Positioning</b>	Acoustic Systems Ranging Systems  Compass Systems	DigiCOURSE Acoustic System Posnet Relative GPS MDL Fanbeam Laser Ranging Unit Input/Output Pro2000 Compasses	Pro2000 Ver 1.57 Ver 1.59 Pro2000	C-O = -0.43° (bearing)
<b>Other Systems</b>	Backup Gyrocompass Primary Gyrocompass Test Pseudo Gyro Prime Fathometer Backup Fathometer	Sperry Mk227 (Gyro #1) Sperry Mk227 (Gyro #2) Posnet rGPS (Gyro #3) Simrad EA-500 18 kHz Xducer Echotrac DF3200 Mk II		C-O = +0.45° C-O = -0.04° C-O = -0.04° No draught correction in sensor* No draught correction in sensor† Xducer depth = *5.94, †5.0
<b>Magnetic declination</b>	+11.103	(From IGRF95 model; 25-Dec-99; Average of 9 corners of Survey Area)		
<b>Geoidal Undulation</b>	-2.624	(From OSU91A model; Average of 9 corners of Survey Area)		
<b>Binning Systems</b>	Real-time binning Post line binning	Spectra Reflex	Ver 7.6.5 Ver 1.7.2	
<b>Processing Systems</b>	Real-time processing Post line processing	Spectra Unavchk	Ver 7.6.5 Ver 1.9.6	

NB : All C-Os are entered in the Spectra Spread Configuration. All data output by the sensors is raw, with no C-O applied.

# P2/94 HEADER NODE NAMING CONVENTION



Each sensor is referenced to a platform. The following Alpha numeric codes are used to refer to the platform

Vessel	<b>V#</b>	<i>where # is replaced by an identifying number</i>
Gun Array	<b>G##</b>	<i>where ## is replaced by an identifying number incrementing from stbd to port</i>
Streamer	<b>S##</b>	<i>where ## is replaced by an identifying number incrementing from stbd to port</i>
Tailbuoy	<b>T##</b>	<i>where ## is replaced by an identifying number incrementing from stbd to port</i>

The sensors are identified by the platform, then by the system type, and finally by an identifying number

Acoustic	<b>T##</b>	<i>where ## is replaced by an identifying number incrementing from front to back</i>
dGPS	<b>G#</b>	<i>where # is replaced by an identifying number incrementing from front to back</i>
Echosounder	<b>E#</b>	<i>where # is replaced by an identifying number incrementing from front to back</i>
Gun String	<b>S#</b>	<i>where # is replaced by an identifying number incrementing from front to back</i>
Gyro	<b>GY#</b>	<i>where # is replaced by an identifying number incrementing from front to back</i>
Laser	<b>L#</b>	<i>where # is replaced by an identifying number incrementing from front to back</i>
Pitch/Roll	<b>PR#</b>	<i>where # is replaced by an identifying number incrementing from front to back</i>
rGPS	<b>R##</b>	<i>where ## is replaced by an identifying number incrementing from front to back</i>
Water Speed	<b>WS#</b>	<i>where # is replaced by an identifying number incrementing from front to back</i>
Velocimeter	<b>V#</b>	<i>where # is replaced by an identifying number incrementing from front to back</i>
User Defined	<b>UD##</b>	<i>where ## is replaced by an identifying number incrementing from front to back</i>

For example T04R01 refers to the rGPS sensor on tailbuoy 4

Exceptions are the compass and depth sensors on the streamers. These are referenced by the following convention

**VC##** *where V is replaced by the vessel number, C by the streamer number, and ## by an identifying number incrementing from front to back*

For example 1608 refers to the 8th compass/depth sensor on vessel 1, cable 6

## VESSEL AND ANTENNAE OFFSETS



	Fore (+)	Stbd (+)	Height (+)
Navigation Reference Point (NRP V1) [ Primary GPS Antenna at sea level ]	0.00	0.00	0.00
Primary GPS Antenna (V1G1-5)	0.00	0.00	20.29
rGPS Antenna (P2/94 offset, V1R01)	0.00	0.00	0.00* (20.29)
Fanbeam Laser Head (V1L1)	0.00	0.00	18.73
Primarty (Simrad) Fathometer	10.71	1.59	-5.94
Backup (Echotrac) Fathometer	-3.90	-8.90	-5.00
Input/Output Hull Acoustic Xducer (V1T01)	-1.51	0.34	-5.60
Gyrocompass 1 (V1GY1)	-3.30	-1.80	-1.80
Gyrocompass 2 (V1GY2) (Primary)	-3.30	0.60	-1.80

NB : All offsets are in metres and are referenced to the NRP

\* Posnet antenna heights are all set to MSL in Spectra as the ranges are slant corrected within the Posnet system

## TAILBUOY OFFSETS

Cable	Tailbuoy ID	TRP Distance from CRP		Tailbuoy Sensor Offsets from TRP			
		Fore (+)	Height (+)	Acoustic ID	Height (+)	rGPS ID	Height (+)
S01	T01	-4732.85	6.00	S01T08	-1.50	T01R01	0.00* (1.80)
S02	T02	-4732.85	6.00	S02T08	-1.50	T02R01	0.00* (1.80)
S03	T03	-4732.85	6.00	S03T08	-1.50	T03R01	0.00* (1.80)
S04	T04	-4732.85	6.00	S04T08	-1.50	T04R01	0.00* (1.80)
S05	T05	-4732.85	6.00	S05T08	-1.50	T05R01	0.00* (1.80)
S06	T06	-4732.85	6.00	S06T08	-1.50	T06R01	0.00* (1.80)

NB : All offsets are in metres and are referenced to the CRP (centre near group) or TRP (tailbuoy antenna at MSL)

\* Posnet antenna heights are all set to MSL in Spectra as the ranges are slant corrected within the Posnet system

# STREAMER POSITIONING SENSOR OFFSETS



## Streamer Acoustic Sensors

CABLE #1		CABLE #2		CABLE #3		CABLE #4		CABLE #5		CABLE #6	
ID #	Fore (+)										
S01T01	-62.67	S02T01	-62.67	S03T01	-62.67	S04T01	-62.67	S05T01	-62.67	S06T01	-62.67
S01T02	-261.87	S02T02	-261.87	S03T02	-261.87	S04T02	-261.87	S05T02	-261.87	S06T02	-261.87
S01T03	-461.07	S02T03	-461.07	S03T03	-461.07	S04T03	-461.07	S05T03	-461.07	S06T03	-461.07
S01T04	-2154.27	S02T04	-2154.27	S03T04	-2154.27	S04T04	-2154.27	S05T04	-2154.27	S06T04	-2154.27
S01T05	-2253.87	S02T05	-2253.87	S03T05	-2253.87	S04T05	-2253.87	S05T05	-2253.87	S06T05	-2253.87
S01T06	-4445.07	S02T06	-4445.07	S03T06	-4445.07	S04T06	-4445.07	S05T06	-4445.07	S06T06	-4445.07
S01T07	-4579.95	S02T07	-4579.95	S03T07	-4579.95	S04T07	-4579.95	S05T07	-4579.95	S06T07	-4579.95

## Streamer Compass Sensors

CABLE #1		CABLE #2		CABLE #3		CABLE #4		CABLE #5		CABLE #6	
ID #	Fore (+)										
1101	+15.65	1201	+15.65	1301	+15.65	1401	+15.65	1501	+15.65	1601	+15.65
1102	-162.27	1202	-162.27	1302	-162.27	1402	-162.27	1502	-162.27	1602	-162.27
1103	-361.47	1203	-361.47	1303	-361.47	1403	-361.47	1503	-361.47	1603	-361.47
1104	-560.67	1204	-560.67	1304	-560.67	1404	-560.67	1504	-560.67	1604	-560.67
1105	-759.87									1605	-759.87
1106	-859.47	1205	-859.47	1305	-859.47	1405	-859.47	1505	-859.47	1606	-859.47
1107	-1058.67									1607	-1058.67
1108	-1158.27	1206	-1158.27	1306	-1158.27	1406	-1158.27	1506	-1158.27	1608	-1158.27
1109	-1457.07	1207	-1457.07	1307	-1457.07	1407	-1457.07	1507	-1457.07	1609	-1457.07
1110	-1755.87	1208	-1755.87	1308	-1755.87	1408	-1755.87	1508	-1755.87	1610	-1755.87
1111	-2054.67	1209	-2054.67	1309	-2054.67	1409	-2054.67	1509	-2054.67	1611	-2054.67
1112	-2353.47	1210	-2353.47	1310	-2353.47	1410	-2353.47	1510	-2353.47	1612	-2353.47
1113	-2652.27	1211	-2652.27	1311	-2652.27	1411	-2652.27	1511	-2652.27	1613	-2652.27
1114	-2951.07	1212	-2951.07	1312	-2951.07	1412	-2951.07	1512	-2951.07	1614	-2951.07
1115	-3249.87	1213	-3249.87	1313	-3249.87	1413	-3249.87	1513	-3249.87	1615	-3249.87
1116	-3548.67	1214	-3548.67	1314	-3548.67	1414	-3548.67	1514	-3548.67	1616	-3548.67
1117	-3847.47	1215	-3847.47	1315	-3847.47	1415	-3847.47	1515	-3847.47	1617	-3847.47
1118	-4146.27	1216	-4146.27	1316	-4146.27	1416	-4146.27	1516	-4146.27	1618	-4146.27
1119	-4345.47	1217	-4345.47	1317	-4345.47	1417	-4345.47	1517	-4345.47	1619	-4345.47
1120	-4544.67	1218	-4544.67	1318	-4544.67	1418	-4544.67	1518	-4544.67	1620	-4544.67

NB : All offsets are in metres and are relative to the Cable Reference Point (CRP) which is the centre of the first group.  
 Inline (fore is +ve) offsets only are given as all other offsets are zero.

# SOURCE POSITIONING SENSOR OFFSETS



SOURCE #1 (STBD)				
Stbd (Outer) String				
	ID #	Fore (+)	Stbd (+)	Up (+)
<b>Acoustic</b>	G01T01	0.00	6.00	-3.00
<b>rGPS</b>	G01R01	0.00	6.00	5.00* (6.0)
<b>Fanbeam</b>	N/A			
<b>Fore D.I.</b>	101	6.60	6.00	1.00
<b>Mid D.I.</b>	105	-1.00	6.00	1.00
<b>Aft D.I.</b>	108	-8.50	6.00	1.00
Centre String				
	ID #	Fore (+)	Stbd (+)	Up (+)
<b>Acoustic</b>	N/A			
<b>rGPS</b>	G01R02	0.00	0.00	5.00* (6.0)
<b>Fanbeam</b>	G01L01	0.00	0.00	5.50
<b>Fore D.I.</b>	201	6.60	0.00	1.00
<b>Mid D.I.</b>	205	-1.00	0.00	1.00
<b>Aft D.I.</b>	208	-8.50	0.00	1.00
Port (Inner) String				
	ID #	Fore (+)	Stbd (+)	Up (+)
<b>Acoustic</b>	G01T02	0.00	-6.00	-3.00
<b>rGPS</b>	G01R03	0.00	-6.00	5.00* (6.0)
<b>Fanbeam</b>	N/A			
<b>Fore D.I.</b>	301	6.60	-6.00	1.00
<b>Mid D.I.</b>	305	-1.00	-6.00	1.00
<b>Aft D.I.</b>	308	-8.50	-6.00	1.00

SOURCE #2 (PORT)				
Stbd (Inner) String				
	ID #	Fore (+)	Stbd (+)	Up (+)
<b>Acoustic</b>	G02T01	0.00	6.00	-3.00
<b>rGPS</b>	G02R01	0.00	6.00	5.00* (6.0)
<b>Fanbeam</b>	N/A			
<b>Fore D.I.</b>	601	6.60	6.00	1.00
<b>Mid D.I.</b>	605	-1.00	6.00	1.00
<b>Aft D.I.</b>	608	-8.50	6.00	1.00
Centre String				
	ID #	Fore (+)	Stbd (+)	Up (+)
<b>Acoustic</b>	N/A			
<b>rGPS</b>	G02R02	0.00	0.00	5.00* (6.0)
<b>Fanbeam</b>	G02L01	0.00	0.00	5.50
<b>Fore D.I.</b>	701	6.60	0.00	1.00
<b>Mid D.I.</b>	705	-1.00	0.00	1.00
<b>Aft D.I.</b>	708	-8.50	0.00	1.00
Port (Outer) String				
	ID #	Fore (+)	Stbd (+)	Up (+)
<b>Acoustic</b>	G02T02	0.00	-6.00	-3.00
<b>rGPS</b>	G02R03	0.00	-6.00	5.00* (6.0)
<b>Fanbeam</b>	N/A			
<b>Fore D.I.</b>	801	6.60	-6.00	1.00
<b>Mid D.I.</b>	805	-1.00	-6.00	1.00
<b>Aft D.I.</b>	808	-8.50	-6.00	1.00

NB. Source offsets are in metres and are relative to the geometric centre of source (COS)

\* Posnet antenna heights are all set to MSL in Spectra as the ranges are slant corrected within the Posnet system

# PARAMETER CHANGES



## VELOCITY OF SOUND

Velocity of sound in water was determined from Temperature/Salinity (TS) Dips taken periodically throughout the survey :

Seq 076-084	1517.6 m/s	Average of top 15 m of water column on 17-Feb-2000
Seq 085-105	1518 m/s	Average of top 15 m of water column on 28-Feb-2000
Seq 106-117	1520 m/s	Average of top 15 m of water column on 10-Mar-2000
Seq 118-147	1516 m/s	Average of top 15 m of water column on 16-Mar-2000
Seq 141-147	1516 m/s	Average of top 15 m of water column on 02-Apr-2000

The fathometer used a fixed value of 1500 m/s throughout the survey within the sensor, except for sequences 024-028 where the value in the Simrad fathometer was changed to 1513 m/s

The depths output to the P1/90 were scaled within the Unavchk processing system using the following values :

Seq 067-084	1514 m/s	Average of complete water column on 10-Feb-2000 & 17-Feb-2000
Seq 085-105	1517 m/s	Average of complete water column on 28-Feb-2000
Seq 106-117	1519 m/s	Average of complete water column on 10-Mar-2000
Seq 118-140	1514 m/s	Average of complete water column on 16-Mar-2000
Seq 141-147	1514 m/s	Average of complete water column on 02-Apr-2000

## POSITIONING SENSOR OFFSET CHANGES

None

## TOWING CONFIGURATION CHANGES

Prior to Seq 090 Guns deployed an additional 10 m, cables and vanes deployed an additional 20 m, to adjust separations following vane wire replacement (which took place prior to Seq 084)

New NRP to source centre inline offset = 325 m

New NRP to centre first group inline offset = 455 m

New source centre to first group inline offset = 130 m

Prior to Seq 105 Minor adjustment of cables (all retrieved 10 m) to improve separations